



Multi-conjugate adaptive optics

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Outline

- In this talk, I will:
 - Present why we need MCAO
 - Show a simple way to control MCAO systems ("star oriented")
 - Show some complications when LGSs are used
 - Variation on MCAO: Layer oriented WFS
 - Some MCAO projects

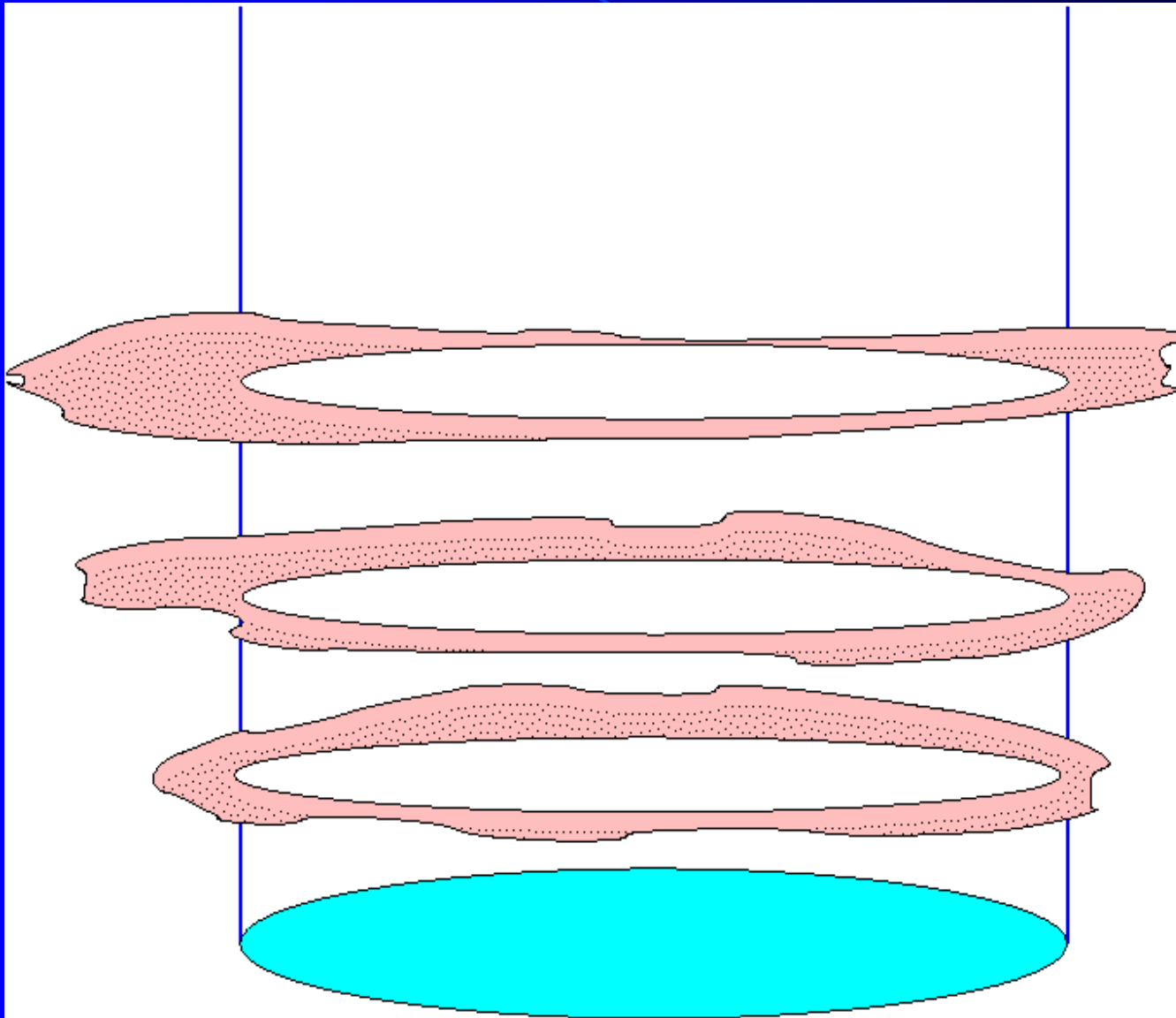


Why MCAO ?

- Main limitations of single star/DM AO:
 - Cone effect → No LGS in the visible on large tel.
 - √ Anisoplanatism → reduces corrected FOV
 - √ ~30" (radius) in IR, ~3" in visible
 - √ PSF variations in FOV make data analysis difficult
- Solutions:
 - use several guide stars to probe larger turbulence volume ("tomography" WFS)
 - use several DMs conjugated to different altitudes, to correct a larger volume of turbulence



On-axis AO

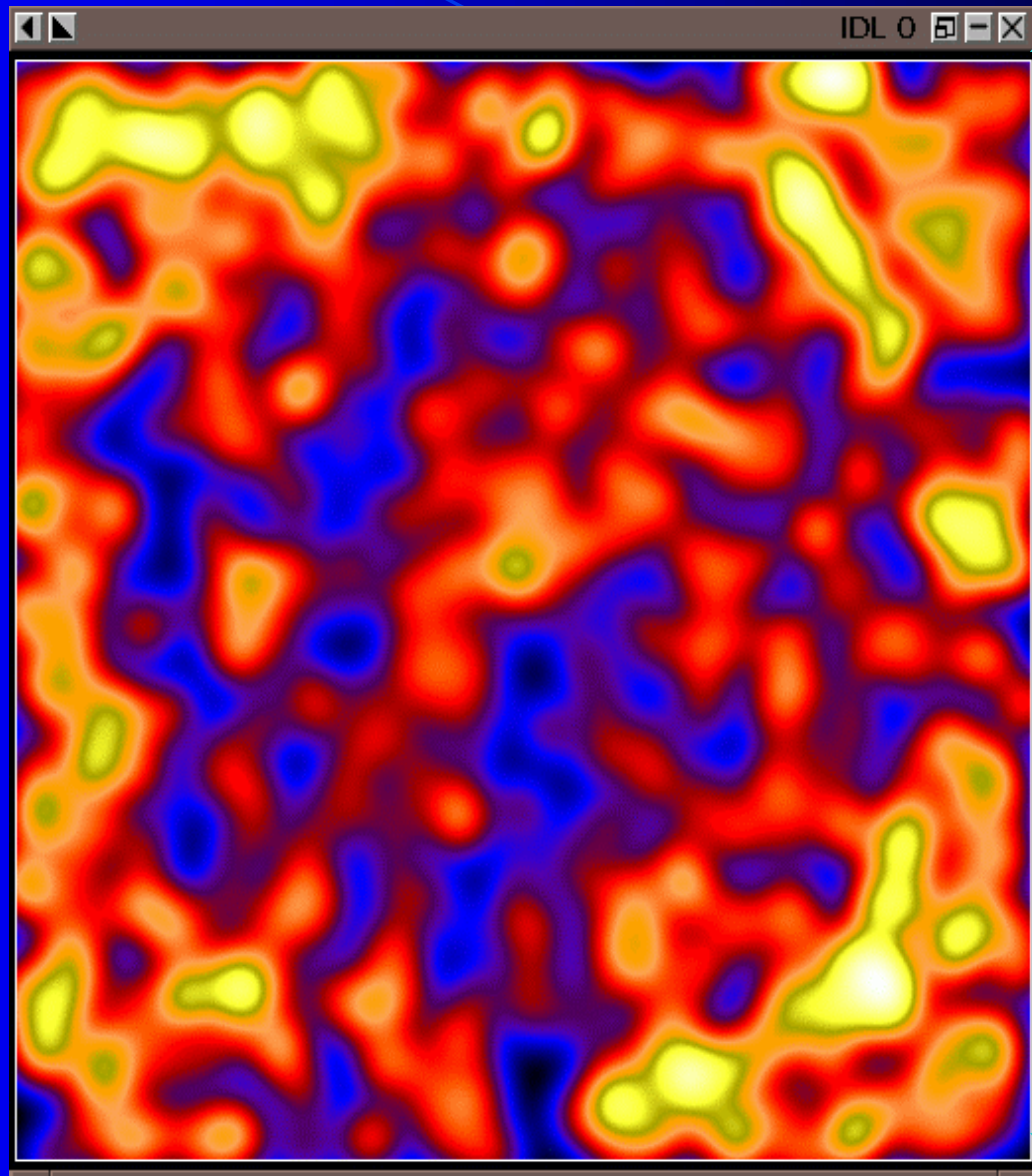




Seeing of 0.5", J band

∅ 80"
J band
1000 stars

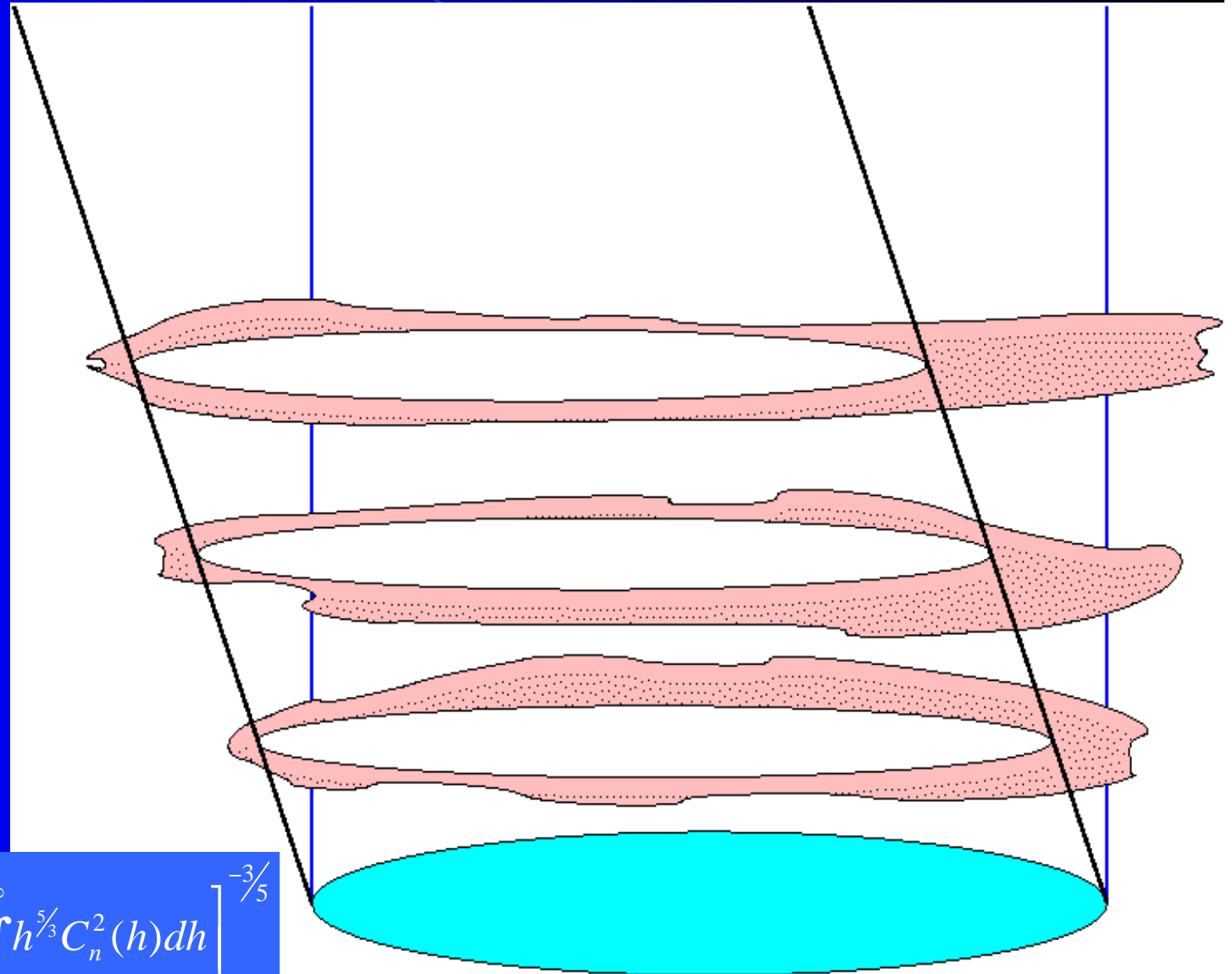
FWHM
~ 0.4"



80"



AO: anisoplanatism



$$\theta_0(\lambda) = \left[2.91k^2 \sec(z) \int_0^{\infty} h^{5/3} C_n^2(h) dh \right]^{-3/5}$$



NGS-AO, J band

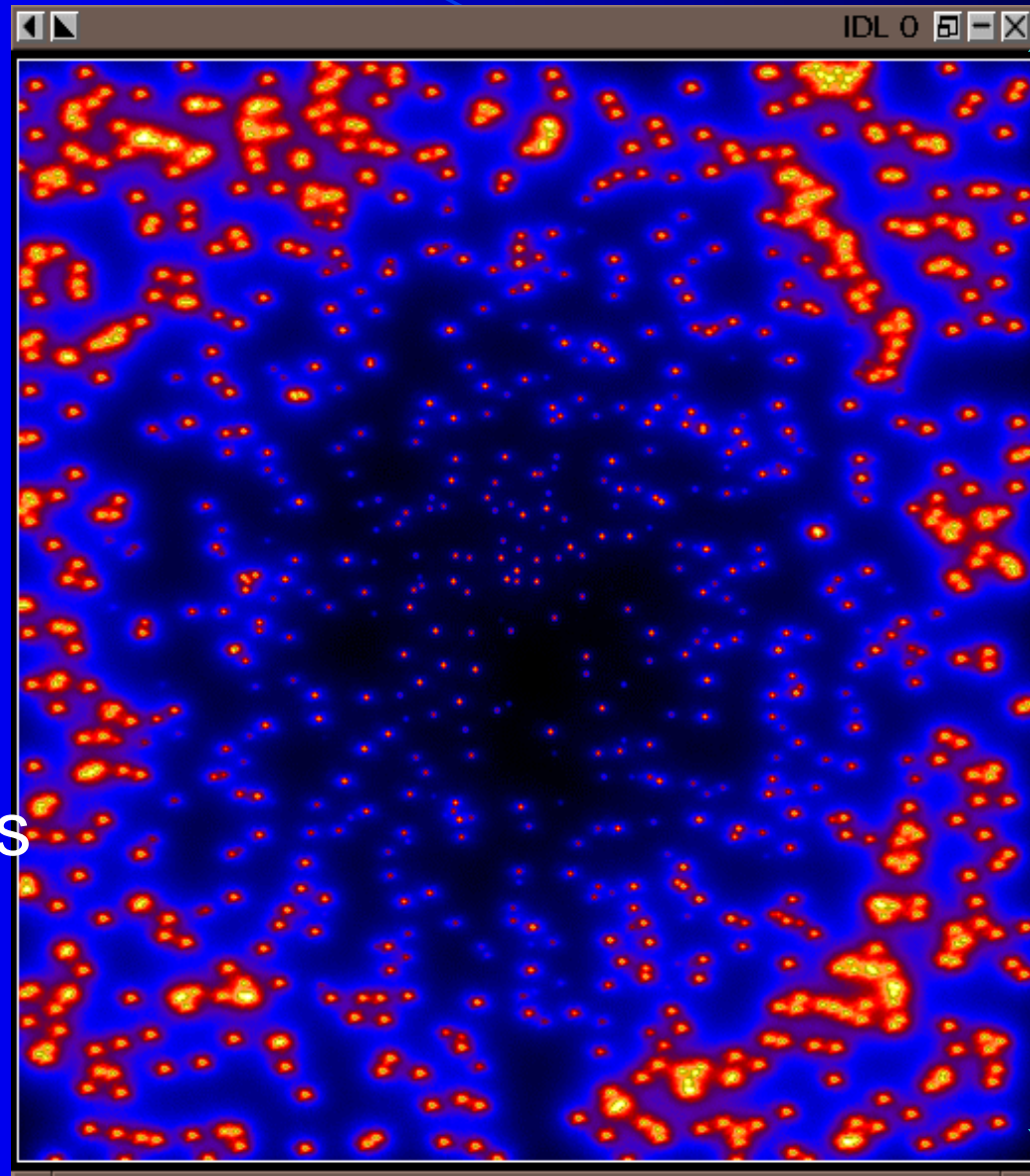
∅ 80"

J band

1000 stars

FWHM

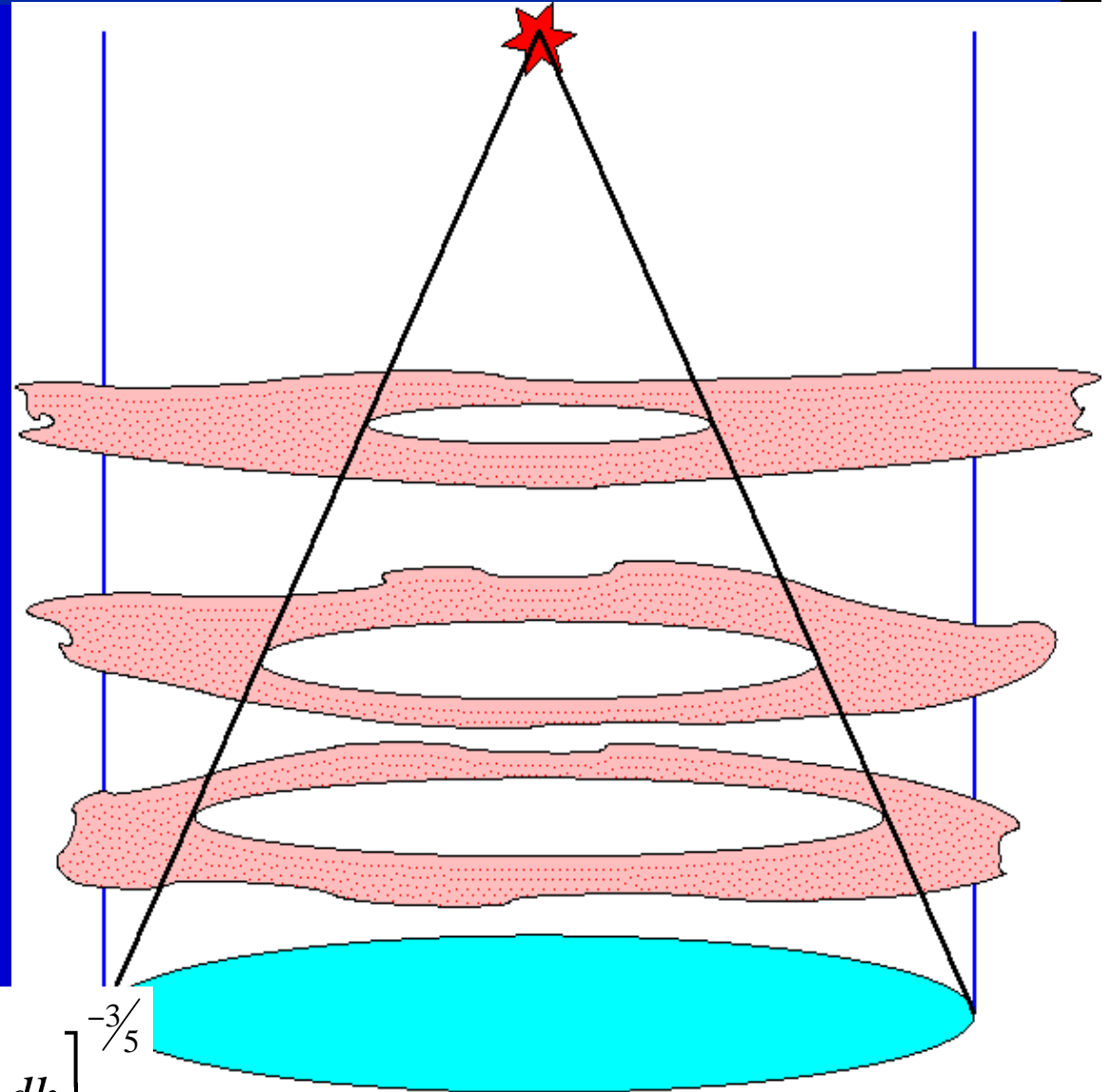
34 → 70 mas



80"



AO: cone effect

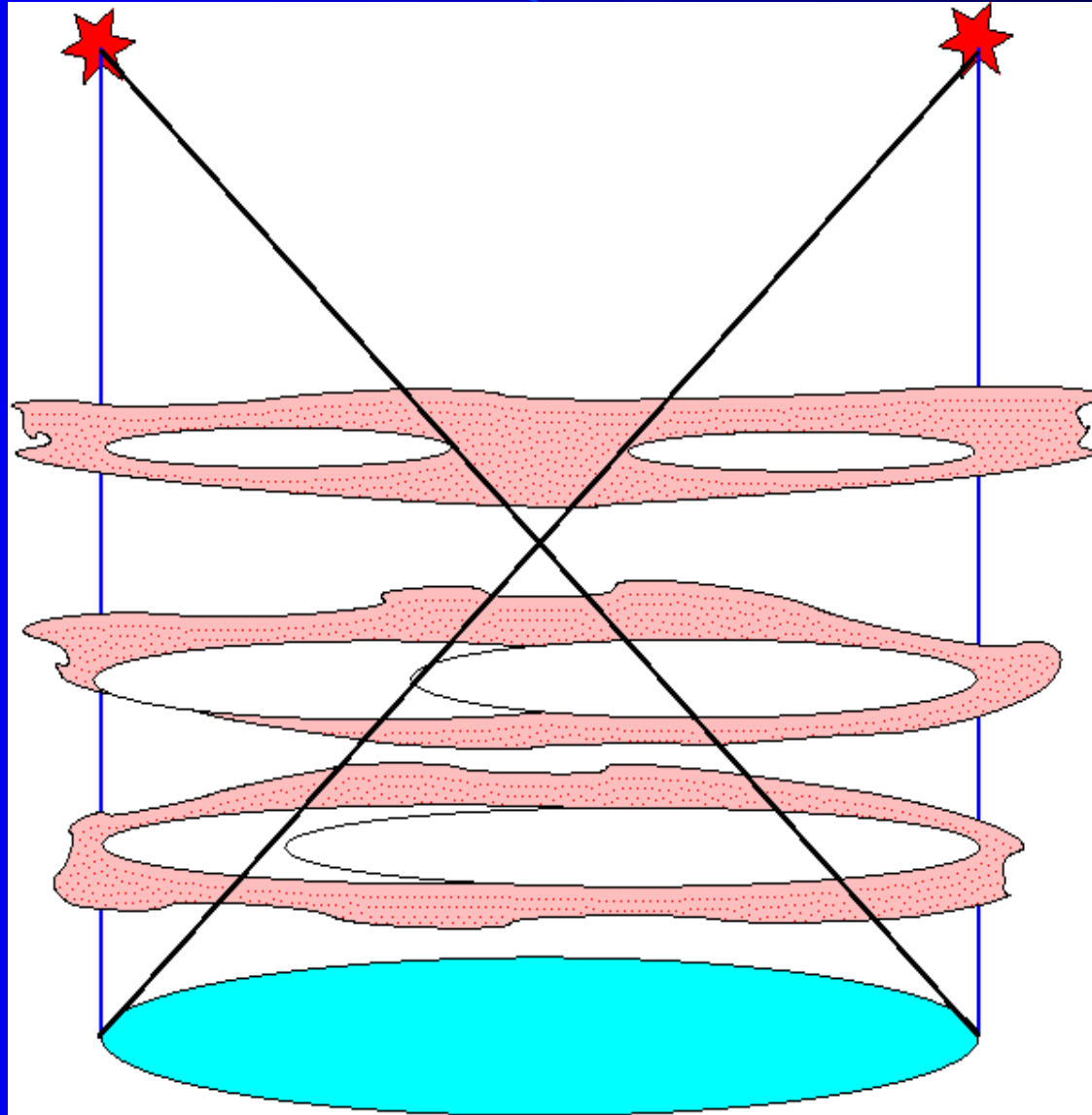


Tyler 94

$$d_0(\lambda) = \left[k^2 \sec(\zeta) \int_0^\infty C_n^2(h) F\left(\frac{h}{H}\right) dh \right]^{-3/5}$$

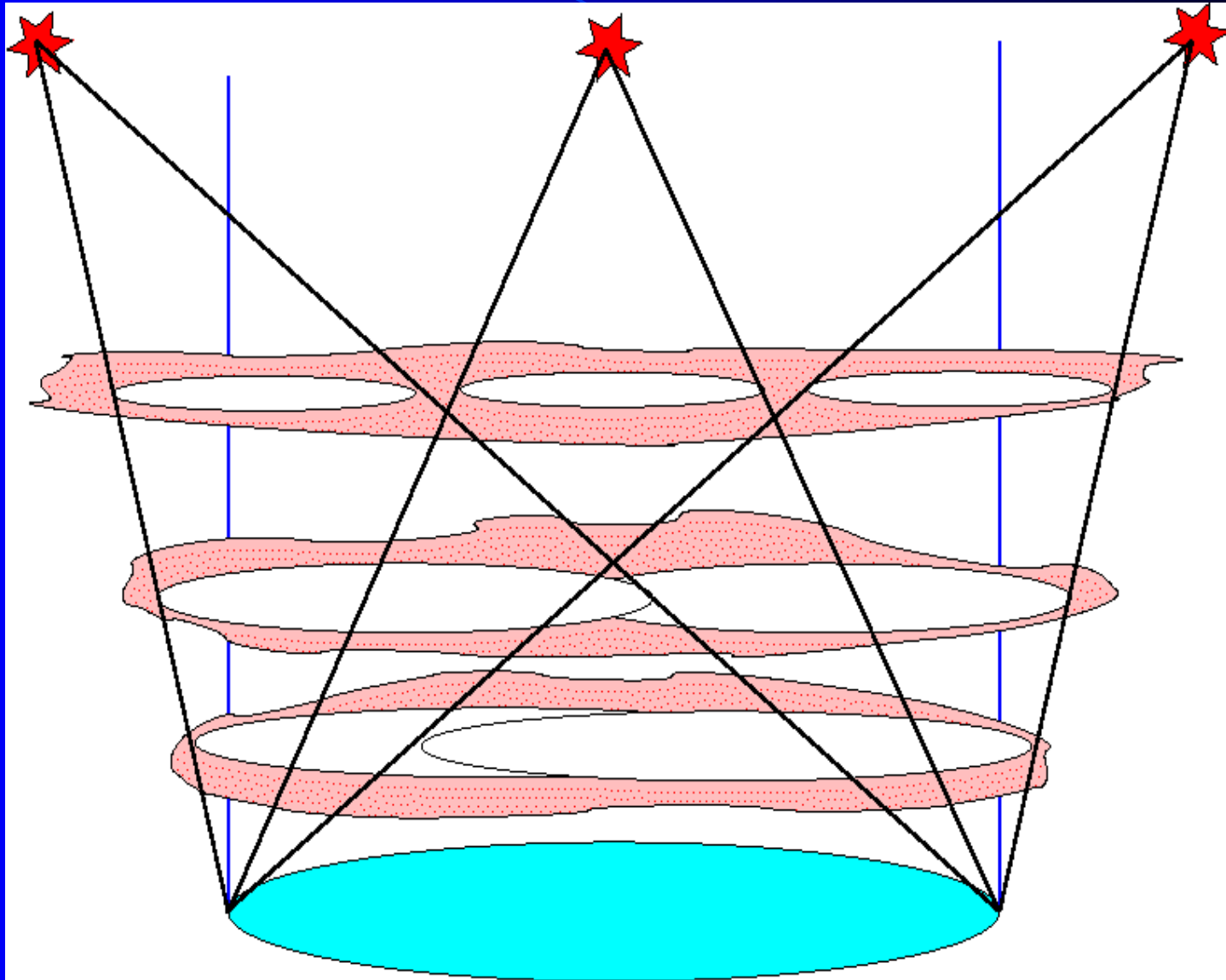


AO: Multiple LGSs





AO: Increasing the FOV





MCAO, J band

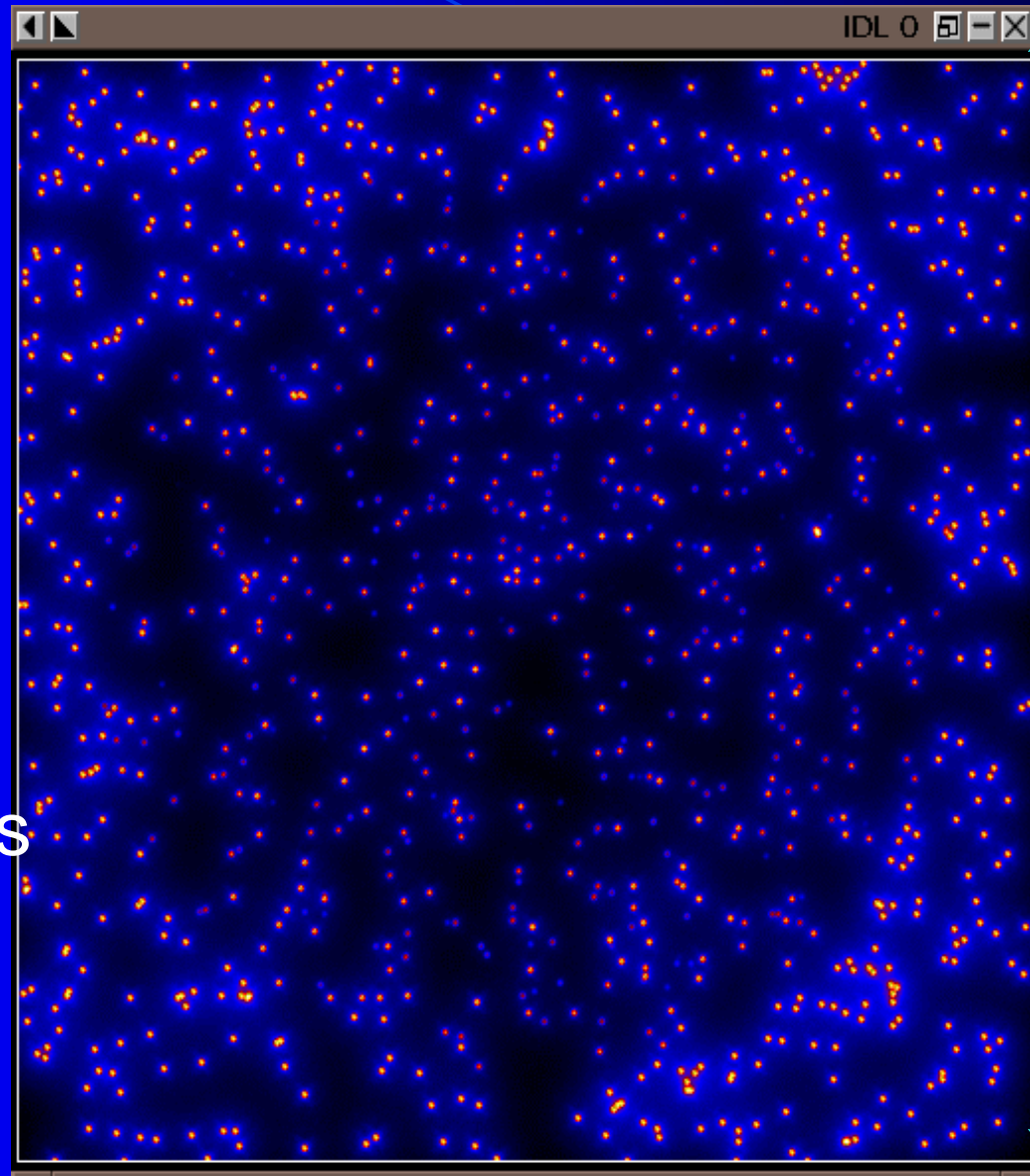
∅ 80"

J band

1000 stars

FWHM

37 → 39 mas

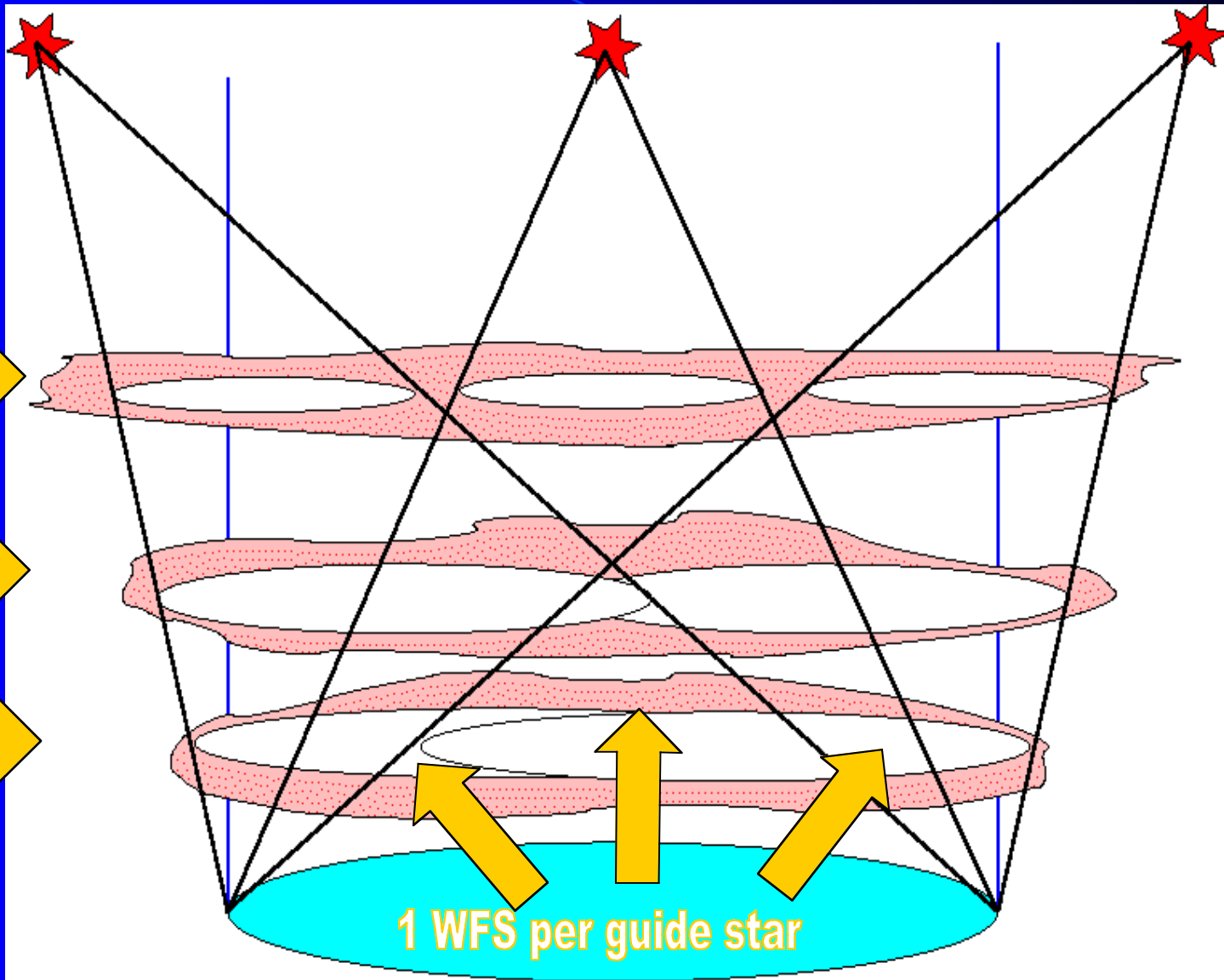
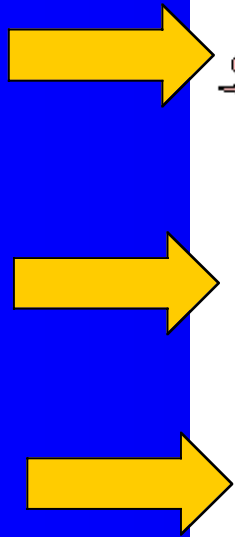


80"



AO: Increasing the FOV

3 DMs to control





Interaction matrix in (MC)AO

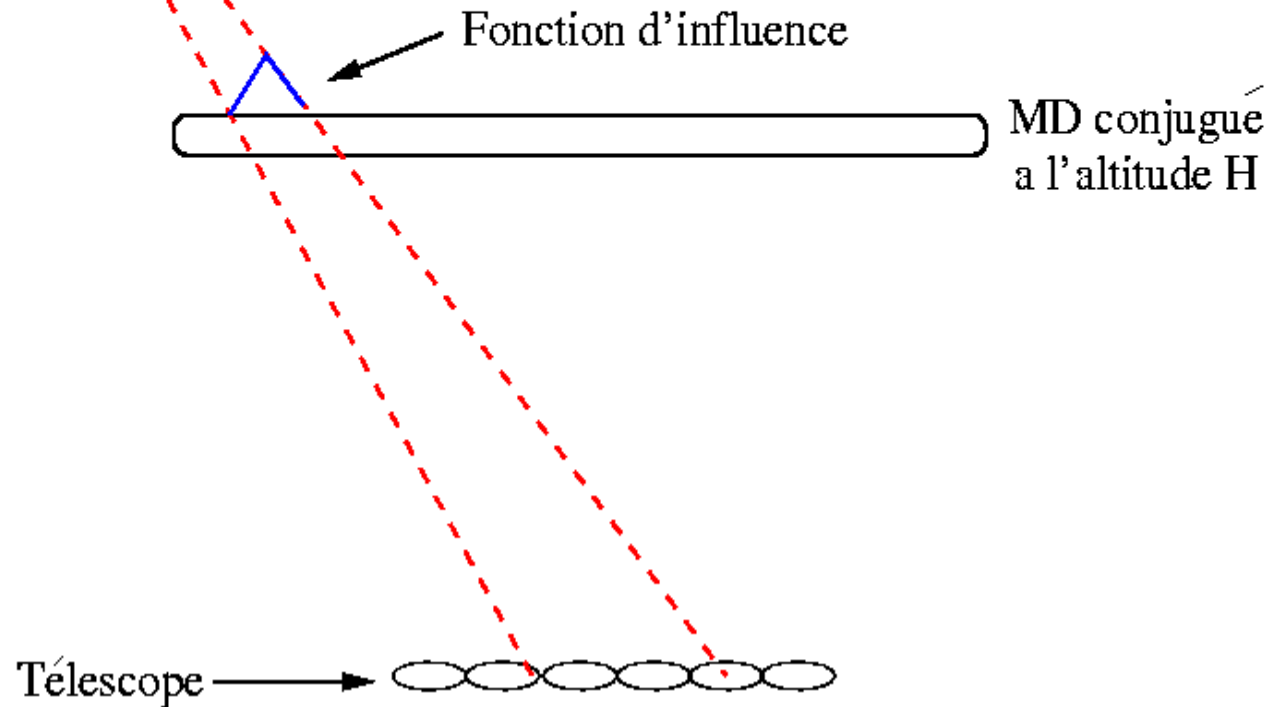
- Move one actuator on the deformable mirror
 - response DM → **influence function**
- **Propagate** this DM shape to the conjugation height of the WFS (here ground)
- measure of the response current WFS (b)
- store b in the **interaction matrix** (M)
 - as many rows as measurements and columns as actuators
- Invert that matrix (+ filter \leftrightarrow piston)
→ command matrix: M^+ (LS estimate)
- v → command c of the DM :

$$\begin{matrix} \mathbf{r} \\ \mathbf{c} \end{matrix} = M^+ \cdot \begin{matrix} \mathbf{r} \\ \mathbf{b} \end{matrix} = (M^t M)^{-1} M^t \cdot \begin{matrix} \mathbf{r} \\ \mathbf{b} \end{matrix}$$



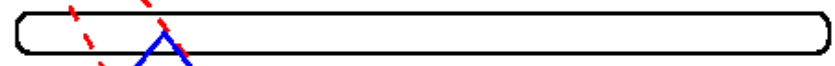
Etoile Laser 1 *

Méthode 3D: Construction de la matrice d'interaction



Etoile Laser 1 *

Méthode 3D: Construction de la matrice d'interaction

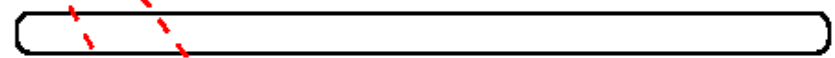


MD conjugué
à l'altitude H



Etoile Laser 1 *

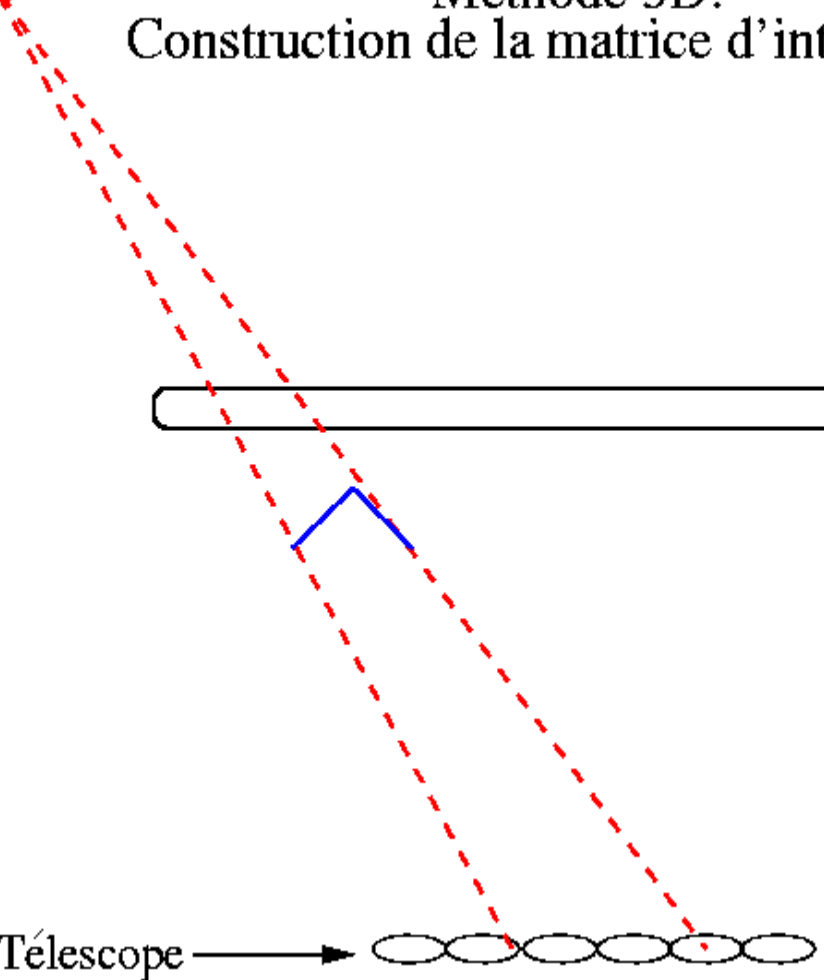
Méthode 3D: Construction de la matrice d'interaction



MD conjugué
à l'altitude H

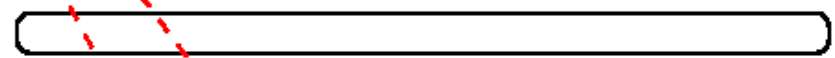


Télescope →

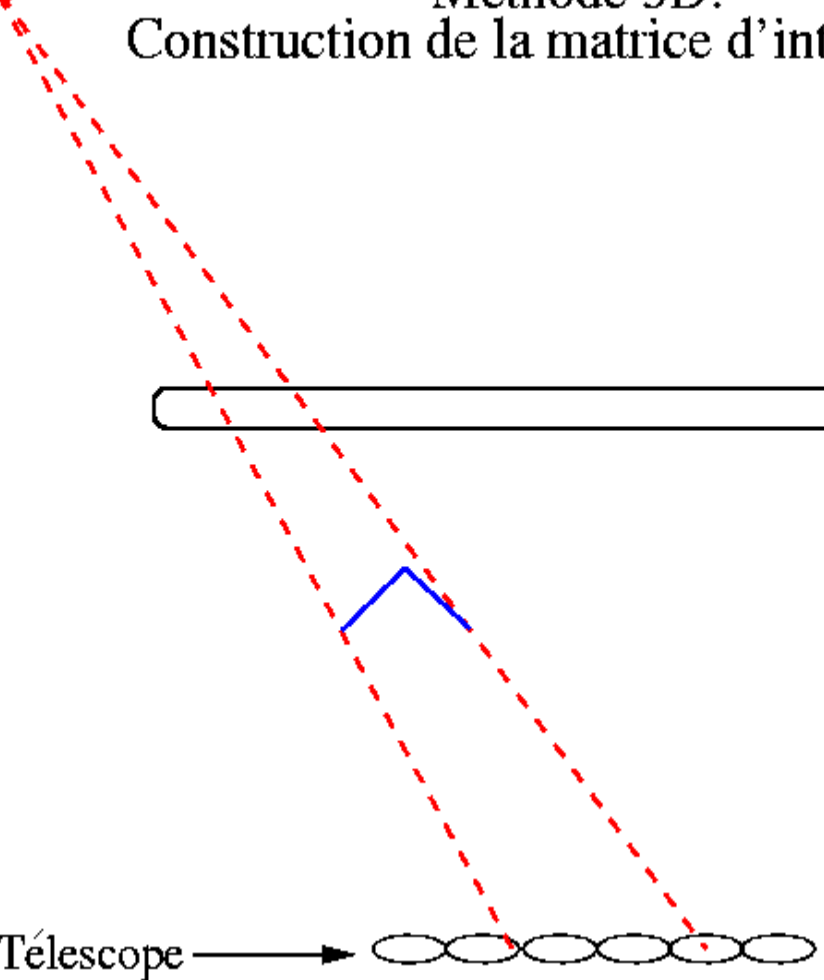


Etoile Laser 1 *

Méthode 3D: Construction de la matrice d'interaction

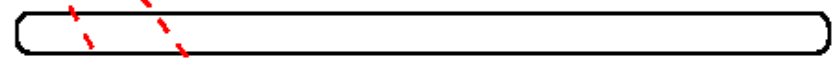


MD conjugué
à l'altitude H

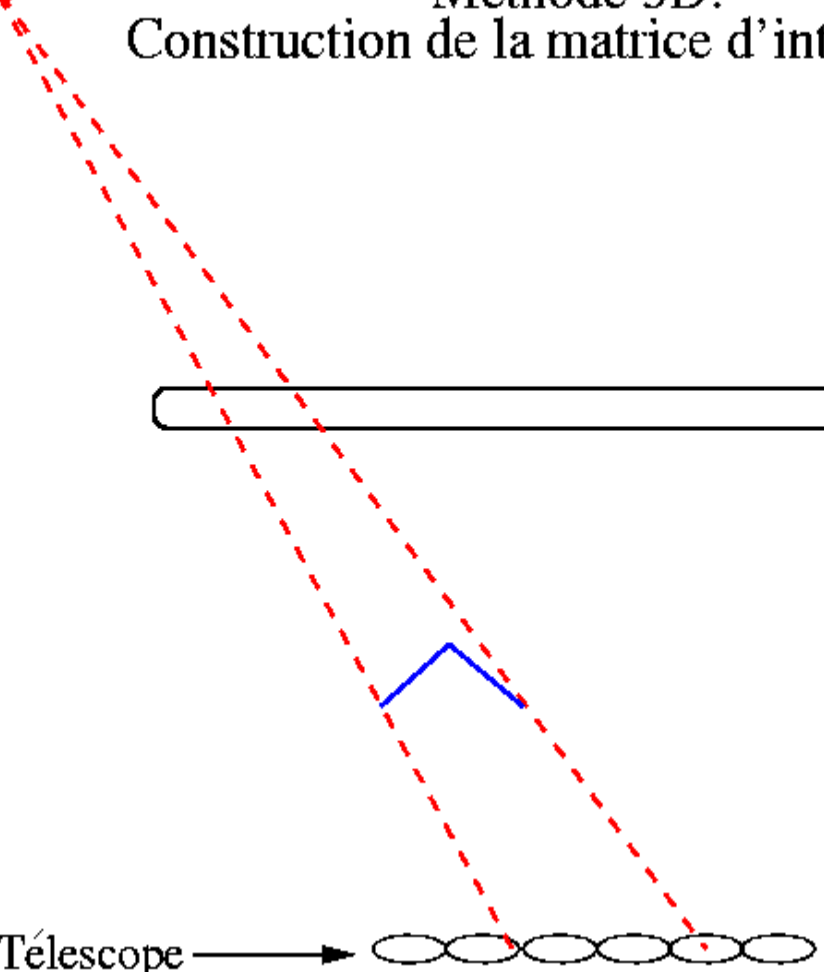


Etoile Laser 1 *

Méthode 3D: Construction de la matrice d'interaction

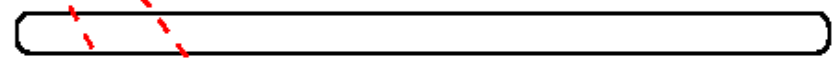


MD conjugué
à l'altitude H

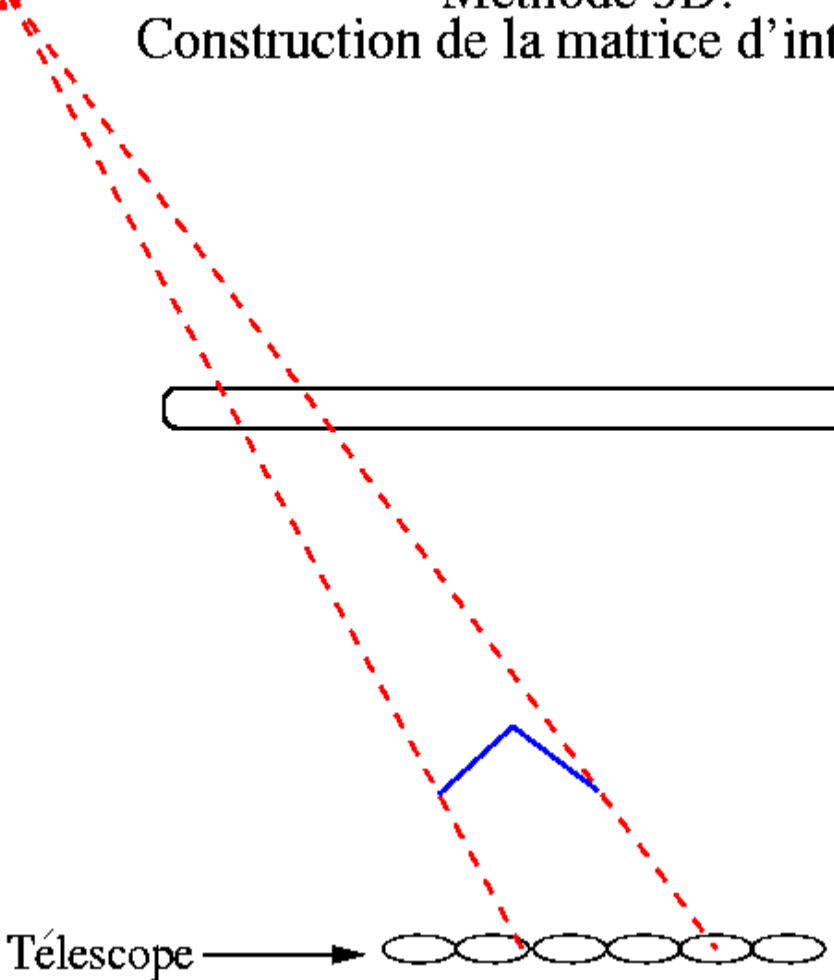


Etoile Laser 1 *

Méthode 3D: Construction de la matrice d'interaction



MD conjugué
à l'altitude H

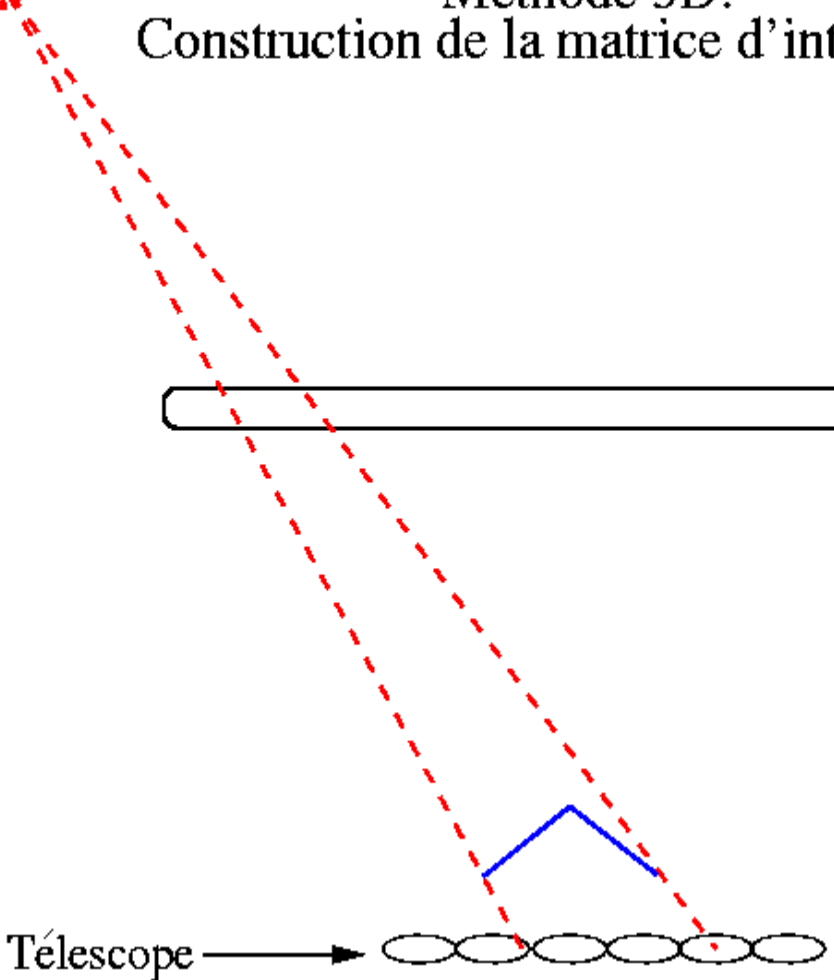


Etoile Laser 1 *

Méthode 3D: Construction de la matrice d'interaction

MD conjugué
à l'altitude H

Télescope →



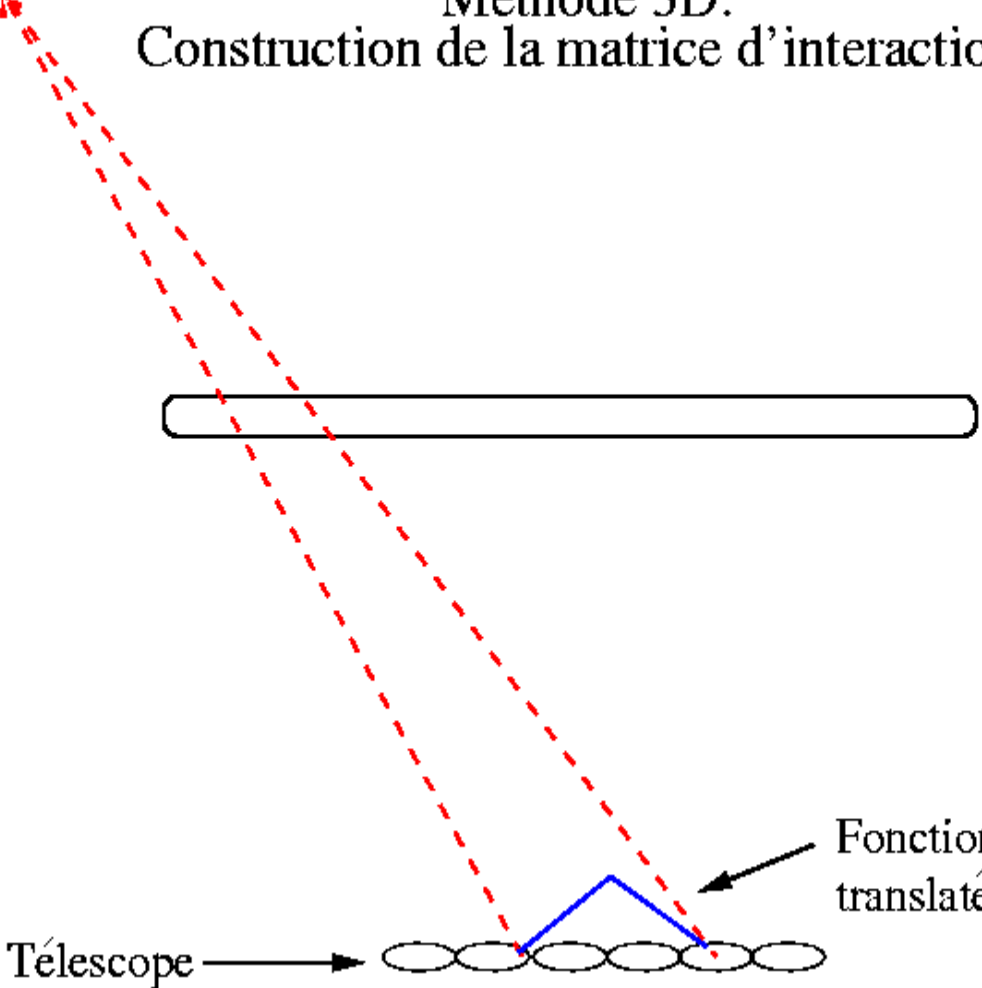
Etoile Laser 1 *

Méthode 3D: Construction de la matrice d'interaction

MD conjugué
à l'altitude H

Fonction d'influence
translatée et dilatée

Télescope →





Interaction matrix

2 DMs (5x5, 7x7)

4 LGS at the edge of the FOV

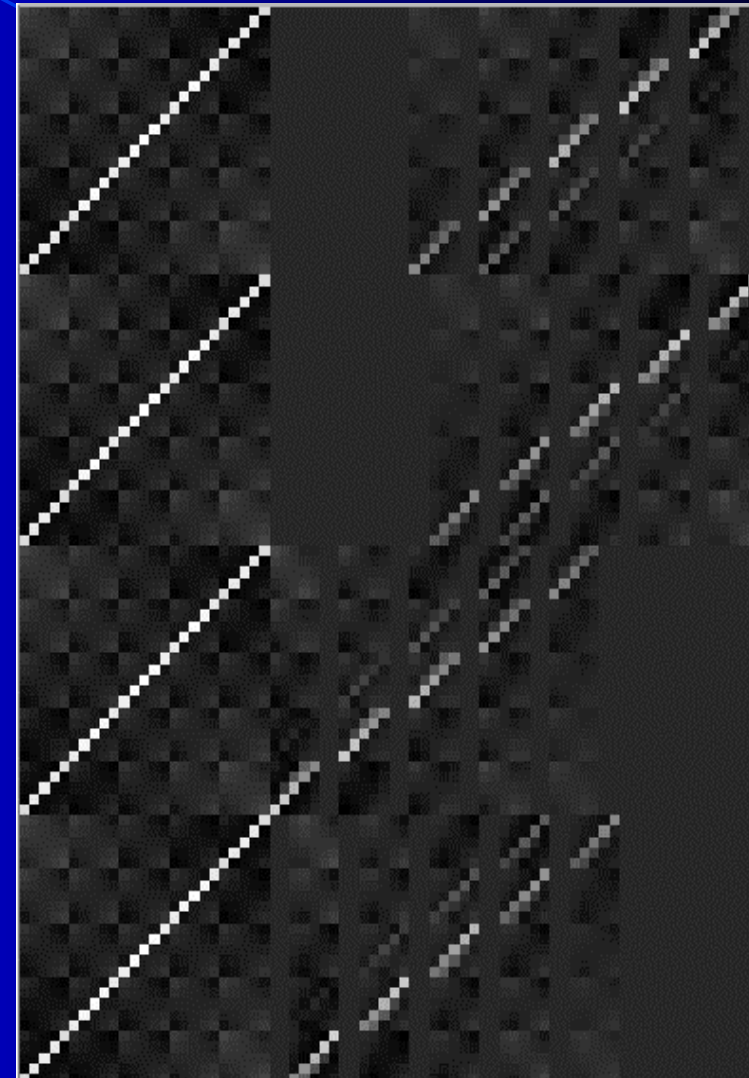
8m tel

LGS 4

LGS 3

LGS 2

LGS 1



Measurement

Ground conjugate DM produces same measurements on all WFSs

DM 1

DM 2



Control of MCAO

- This was the easiest way to control MCAO
- More performance w/ Regularization
- Minimum variance / optimal estimators
- Kalman filtering (closed loop control)
- Sparse matrix methods (for ELTs)
- CG minimization methods (for ELTs)
- [...]

